

Balazs Andras Kovacs

Curriculum Vitae

Educations

Schools

- 2015–2017 Master of Mechanical Engineering, Budapest University of Technology and Economics, Applied Mechanics, Budapest, Grade: Excellent. Thesis title: Development and test of a virtual pole balancing platform
- 2011–2015 **Bachelor of Mechanical Engineering**, Budapest University of Technology and Economics, Mechanical Developer, Budapest, Grade: Excellent. Thesis title: Motion control considering actuator saturation
- 2007–2011 High school studies, ELTE Apaczai Csere Janos Practice School, Budapest.

Experiences

Vocational

2016–present **MTA-BME Lendulet Human Balancing Research Group**, Budapest. Research Assistant

- $\circ~$ Publications in a scientific paper and a conference.
- Participation at the National Student Scientific Conference

2016 Robert Bosch Kft., Budapest.Simulation Engineer Trainee• Wiper Systems Simulation Engineer

2014 C3D Kft., Budapest.

• Summer internship: Simulation Engineer

Miscellaneous

2016–2017 Lockdown Worldwide Kft., Debrecen. Industrial Designer o Design and production of game items

	Publications	
	Journal	
	Kovacs BA., Insperger T, Retarded, neutra models for balancing using an acceleromete and Control, Springer 2017, 10.1007/s4043	r, International Journal of Dynamics
	Conference	
extended abstract	Kovacs BA, Insperger T, Different model 9th European Nonlinear Dynamics Confere 2017	<u> </u>
	Languages	
Hungarian	mother tongue	
English	_	Fluent conversation
French	Basic	Basic words and phrases only
	Computer skills	
Basic systems	MS Office (Excel, Word, PowerPoint), $\ensuremath{\mathbb{I}}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\xspace{-1.5}\$	
Vocational software	MATLAB, Ansys, Solidworks, AutoCAD, Mathematica	
0 0	C,C#, Python,Java	
languages	, , , , ,	
languages		
languages	Other skills	

Miscellaneous making of FEM, CFD and dynamical simulations, measurement setups good working capacity, reliability, sociability

— Interests

research: dynamical systems, control theory, differential equations programming: software development, micro-controllers

sport: basketball, snowboarding